Inspection and Test Report

for Kollmorgen Lift Control MPK400/MPK411



Initial Electrical Test of the Lift Control System by the Lift Installer in accordance with BS7671:2008

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Please note:

The manufacturing process of the Kollmorgen control system includes a test procedure, which is carried out in accordance with VDE0660 Part 600 and incorporates elements of the initial electrical test as laid out in DIN VDE 0100 Part 600. The initial electrical test must only be carried out by an authorised and competent person as defined in BS7671:2008. Every control system must be tested on site throughout the installation and on completion. This inspection and test report is intended to help with the documentation of test results. Please complete and tick as required.

	Lift Details				Date of the	Test:						
Site I	Reference:	Co	ntroller No.:		Year of Manufa	cture:						
Custo	omer Lift Ref. No.:				Groups	only: Lift	No of					
Lift C	`ampany											
LIIL	Company:				Name of 1	ester			_			
1	General	(Record of Nominal Data)		Automatic Di	sconnection of the	Supply in a	cc. with 4.3	V	1			
_		(necona en neconinal zata)							ı			
1.0	Earthing System	☐ TNC ☐ TNC-S	☐ IT	ПП	Trip Charact	eristic						
	Overcurrent Protec	ctive Device / RCD / Insulation Mo	n. Device	Legende	NH Z B	C gl	Nominal / Trip					
1.1	Nominal / trip curr	ent: Power circuit		F1A-1C			A /A	7]			
1.2	Nominal / trip curr	ent: Control circuit		F1			A /A	1 []			
1.3	Nominal / trip curr	ent: Safety circuit		F3			A /A	7]			
1.4	Nominal / trip curr	ent: Lift car circuit		F90			10A / 50A	7]			
1.5	Nominal / trip curr	ent: Shaft & machine room circuit		F99			A /A	<u>۱</u> []			
1.6	Nominal / trip curr	ent: Door operator 1 circuit		F40A			A /A	7]			
1.7	Nominal / trip curr	ent: Door operator 2 circuit		F40B			A /A	\sqcup	j			
1.8	Nominal / trip curr	ent: Machine brake circuit		F7			A /A	Ĭ	j			
1.9*							A /A	7	j			
1.10*							A /A		j			
	* = available for additio	ns		Typ Z = 3,5 x I-Nei	nn, Typ B = 5 x I-Nenn, Typ	C = 10 x I-Ner	nn, Typ D = 15 x I-Nen	n *:	1			
2	Visual Inspection	(Inspection of the Complete Lift C	Control System	n with Power [Disconnected)	OK= ☑	Commen	ts				
2.0	A visual inspection	of the control system does not sh	ow any safet	ty relevant iss	sues:							
2.1	Correct selection a	nd installation of components and	d cable (insta	llation, fitting	g, protection class	, 🔲						
2.1	protection against	direct contact, labelling and cable	installation/	termination)	:							
2.2	All screw terminals	and connections to components	are correctly	tightened fo	llowing transport:	: 🗆						
2.3	Main isolator (labe	lling and lock-off facility present):										
2.4	Safe accessibility o	f switch gear (adequate space for	hand operati	ion):								
2.5	Earthing conductor	r and connections: correct equipo	tential bondi	ng of all lift s	ystem component	ts:						
2.6	Safety measures fo	or inverters: Protection of the inve	rter supply c	arried out in	accordance with							
2.6	manufacturer's ins											
2.7	SELV / PELV requir	ements fulfilled (and separate fro	m other circu	ıits):								
2.8	Protective covers,	documentation, data plates and s	afety notices	are present:								
2.9		tructions, warnings and safety rec	uirements h	ave been adh	nered to:							
	Z _S = Earth fault loop imp	pedance										
3	Checks	<u>↑</u> Follow	Manufacturer	s' Instructions		ОК= 🗹	Commen	ts				
3.1	Test RCD (if present)	by activating the test button:						m	_ A			
3.2		coring device (if present) by activating	the test butto	n:				m	_			
3.3		protection (if present) by activating the			Thermal ove	erload 🔲	set to _		Α			
3.4*						$\overline{\Box}$	_		_			

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for Kollmorgen Lift Control MPK400/MPK411



Please Note:					
⚠ Disconne	ect! Carry out insulat	ion resistance tests only with	the supply disconne	cted.	Test Object
⚠ For testi	ng in TNC systems te	mporarily disconnect the PE-	N link in the distribut	ion board.	BISO
⚠ Check the	battery charge of the t	est instruments.			
Disconne	ct the supplies to the do	oor operator(s) and inverter(s). T	he safety circuit		
must be n	nade (closed). Measure	circuits with contactor contacts	in sections.		
Select the	correct test voltage:	250V for SELV \leq 50V U _N	Ins. Res. ≥0,5MΩ		PE N L
		500V for line voltage ≤ 500V	Ins. Res. ≥1,0MΩ		
Measure i	nsulation resistance bety	ween each line conductor and the	circuit protective or eart	hing conductor.	(MΩ) (<u>600</u> V)
⚠ Reinstate	the PE-N link after the i	nsulation resistance test.	Link has been reins	tated	
	When testing circ	uits with electronic components	present, L and N need t	o be linked! $ ightarrow$	Test Instruments

4.1	Isolationswiderstand (R-ISO)	Messung zwischen Außenleitern und PE	Freischalten	OK = <u>₩</u>	Comments
4.1.1 Insulation resistance		Control system main supply	X0: PE-N/L	1/L2/L3 🔲	ΜΩ
		Machine	X0: PE-	-U/V/W □[ΜΩ
4.1.2	Insulation resistance safety circuit	(safety circuit must be closed for the test)	X1: Pl	E-7	ΜΩ
4.1.3	Insulation resistance lighting cct.	Lighting/sockets: lift car and shaft	X1: PI	E-L4/L5 🔲	ΜΩ
		Lighting/sockets: machine room	X1: PI	E-L7/L8 🔲	ΜΩ
4.1.4	*				ΜΩ
	* = available for additions				_
4.2	Earth Fault Loop Impedance (ZS)	Test Line Conductors and PE		ок = 🗹	Comments
	ZS = sum of the supply impedance and fina	al circuit resistance [ZS = Ze + (R1 + R2)]		*4	
4.2.1	Earth fault loop impedance	Control system main supply	X0: PE-N/L	1/L2/L3 □	Ω

4.2	Earth Fault Loop Impedance (ZS)	Test Line Conductors and PE	OK = ✓	Comments
	ZS = sum of the supply impedance and fine	al circuit resistance [ZS = Ze + (R1 + R2)]	*4_	
4.2.1	Earth fault loop impedance	Control system main supply	X0: PE-N/L1/L2/L3 □	Ω
	(doesn't work between drive - motor)	Motor (PE minimum csa 10mm²)	X0: PE-U/V/W 🔲	Ω
4.2.2	Safety circuit	(safety circuit must be closed for the test)	B2A: Z _S ≤ 21Ω □	Ω
		Expect 0,25 Ω per landing contact.		
4.2.3	Other circuits	Lighting/sockets: lift car and shaft	with B10A 🔲	Ω
		Lighting/sockets: machine room	Z _S ≤ 4,2Ω	Ω
4.2.4	*			Ω

^{*4 =} Compare the ZS measurements with the maximum permissible values in Table 4.2.6. In case of frequency drives - motor this is not possible, because there is up to 12kHz switching frequency. Make sure the ground connection to the motor is $<0,1\Omega$.

4.2.5	Achievement of the Safety Objective in TNS Systems.	Max. Disconnection Times in TN-Systems according to BS7671:2008								
	Where Z_S values are too high, the $Z_S \le U0/Ia$		Nom. Voltage	Disconnection Time						
A	maximum disconnection times must be reduced through	Final circuits (sockets or	≤230V~	0,4s						
4	additional measures. This can be achieved e.g. with a	fixed appliances) up to 32A	≤400V~	0,2s						
	type B RCD 30mA or additional equipotential bonding.	Supplies exceeding 32A	≤400V~	5,0s						

Protection potential equalization = potential equalization (old name).

4.2.6 Source: BS7671:2008 Earth Fault Loop Impedance (ZS) Tables 41.2, 41.3 and 41.4 for TN Systems

edanc	e (ZS)	for (gC	a) fuse	s to BS	88-2.	2 and E	3S 88-6	5								
6	10	16	20	25	32	40	50	63	80	100	125	100	125	160	200	Α
-	-	8,52	5,11	2,7	1,77	1,44	1,04	-	-	-		-	-	-	-	Ω
-	-	13,5	7,42	4,18	2,91	2,3	1,84	1,35	1,04	0,82	0,57	0,42	0,33	0,25	0,19	Ω
edanc	e (ZS)	for cire	cuit bre	akers	with 0	.4s dis	connec	tion ti	me acc	ording	to BS	EN 608	398			
6	10	16	20	25	32	40	50	63	80	100	125	160	200	125	160	Α
7,67	4,6	2,87	2,3	1,84	1,44	1,15	0,92	0,73	0,57	0,46	0,37	-	-	-	-	Ω
3,83	2,3	1,44	1,15	0,92	0,72	0,57	0,46	0,36	0,29	0,23	0,18	-	-	-	-	Ω
	6 - - pedanc 6 7,67	6 10 pedance (ZS) 6 10 7,67 4,6	6 10 16 8,52 13,5 Declare (ZS) for circle 6 10 16 7,67 4,6 2,87	6 10 16 20 8,52 5,11 13,5 7,42 Declare (ZS) for circuit bree 6 10 16 20 7,67 4,6 2,87 2,3	6 10 16 20 25 8,52 5,11 2,7 13,5 7,42 4,18 Declare (ZS) for circuit breakers 6 10 16 20 25 7,67 4,6 2,87 2,3 1,84	6 10 16 20 25 32 8,52 5,11 2,7 1,77 13,5 7,42 4,18 2,91 Declare (ZS) for circuit breakers with 0 6 10 16 20 25 32 7,67 4,6 2,87 2,3 1,84 1,44	6 10 16 20 25 32 40 8,52 5,11 2,7 1,77 1,44 13,5 7,42 4,18 2,91 2,3 Declare (ZS) for circuit breakers with 0.4s discrete for the control of the con	6 10 16 20 25 32 40 50 8,52 5,11 2,7 1,77 1,44 1,04 13,5 7,42 4,18 2,91 2,3 1,84 pedance (ZS) for circuit breakers with 0.4s disconnected 10 16 20 25 32 40 50 7,67 4,6 2,87 2,3 1,84 1,44 1,15 0,92	8,52 5,11 2,7 1,77 1,44 1,04 13,5 7,42 4,18 2,91 2,3 1,84 1,35 redance (ZS) for circuit breakers with 0.4s disconnection times 6 10 16 20 25 32 40 50 63 7,67 4,6 2,87 2,3 1,84 1,44 1,15 0,92 0,73	6 10 16 20 25 32 40 50 63 80 8,52 5,11 2,7 1,77 1,44 1,04 13,5 7,42 4,18 2,91 2,3 1,84 1,35 1,04 pedance (ZS) for circuit breakers with 0.4s disconnection time according to the control of th	6 10 16 20 25 32 40 50 63 80 100 8,52 5,11 2,7 1,77 1,44 1,04 13,5 7,42 4,18 2,91 2,3 1,84 1,35 1,04 0,82 Declance (ZS) for circuit breakers with 0.4s disconnection time according 6 10 16 20 25 32 40 50 63 80 100 7,67 4,6 2,87 2,3 1,84 1,44 1,15 0,92 0,73 0,57 0,46	6 10 16 20 25 32 40 50 63 80 100 125 8,52 5,11 2,7 1,77 1,44 1,04 13,5 7,42 4,18 2,91 2,3 1,84 1,35 1,04 0,82 0,57 Declance (ZS) for circuit breakers with 0.4s disconnection time according to BS 6 10 16 20 25 32 40 50 63 80 100 125 7,67 4,6 2,87 2,3 1,84 1,44 1,15 0,92 0,73 0,57 0,46 0,37	6 10 16 20 25 32 40 50 63 80 100 125 100 8,52 5,11 2,7 1,77 1,44 1,04 13,5 7,42 4,18 2,91 2,3 1,84 1,35 1,04 0,82 0,57 0,42 Declance (ZS) for circuit breakers with 0.4s disconnection time according to BS EN 608 6 10 16 20 25 32 40 50 63 80 100 125 160 7,67 4,6 2,87 2,3 1,84 1,44 1,15 0,92 0,73 0,57 0,46 0,37 -	6 10 16 20 25 32 40 50 63 80 100 125 100 125 8,52 5,11 2,7 1,77 1,44 1,04 13,5 7,42 4,18 2,91 2,3 1,84 1,35 1,04 0,82 0,57 0,42 0,33 pedance (ZS) for circuit breakers with 0.4s disconnection time according to BS EN 60898 6 10 16 20 25 32 40 50 63 80 100 125 160 200 7,67 4,6 2,87 2,3 1,84 1,44 1,15 0,92 0,73 0,57 0,46 0,37	6 10 16 20 25 32 40 50 63 80 100 125 100 125 160 8,52 5,11 2,7 1,77 1,44 1,04 13,5 7,42 4,18 2,91 2,3 1,84 1,35 1,04 0,82 0,57 0,42 0,33 0,25 Declance (ZS) for circuit breakers with 0.4s disconnection time according to BS EN 60898 6 10 16 20 25 32 40 50 63 80 100 125 160 200 125 7,67 4,6 2,87 2,3 1,84 1,44 1,15 0,92 0,73 0,57 0,46 0,37	6 10 16 20 25 32 40 50 63 80 100 125 100 125 160 200 8,52 5,11 2,7 1,77 1,44 1,04 13,5 7,42 4,18 2,91 2,3 1,84 1,35 1,04 0,82 0,57 0,42 0,33 0,25 0,19 redance (ZS) for circuit breakers with 0.4s disconnection time according to BS EN 60898 6 10 16 20 25 32 40 50 63 80 100 125 160 200 125 160 7,67 4,6 2,87 2,3 1,84 1,44 1,15 0,92 0,73 0,57 0,46 0,37

Most of the test instruments will show the tipp current automaticly during the loop imdedance margement. With this information the disconnection time Can also be determind.

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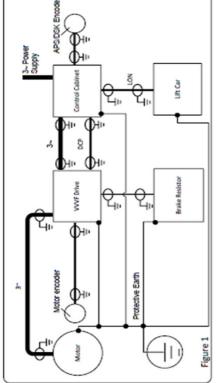
4.3	4.3 Check Automatic Disconnection of the Supply by way of Earth Fault Loop Impedance and Trip Characteristic																
Maximum Earth Fault Loop Impedance (ZS) for circuit breakers with disconnection time ≤ 5 s with U0 of 230V																	
Nor	ninal circuit breakers [A] 2	4	6	10	16	20	25	32	35	40	50	63	Α	zs =	(Uo -	U)/I-Last
Cha	rakteristik B	7,67	4,6	2,87	2,3	1,84	1,44	1,15	0,92	0,73	0,57	0,46	0,37	Ω	ZS(n	n) ≤ 2,	/3 x (Uo/la)
Charakteristik C 3,83 2,3 1,44 1,15 0,92 0,72 0,57 0,46 0,36 0,29 0,23 0,18 Ω																	
wheth ZS = (2	Example: a final circuit (pit socket) has a no-load voltage of 233V. After connecting a 500W lamp the voltage reduces to 229V with a current of 2.2A. Check whether a B10A MCB can be used. ITrip = $5 \times 10A = 50A$ $S = (233V - 229V) / 2,2A = 1,82\Omega$ $S = (233V - 229V) / 2,2A = 1,82$																
4.4	Earth Continuity (Guide: E	arthin	g Cond	luctor	<1Ω, N	Main Pr	otectiv	e Bond	ding Co	onduct	tors < 0	,1Ω)	i.O.=	Ø	Co	omments
4.4.1	Controller PE to motor								(PE mi	inimu	ım csa	a = 10	mm²			
	Check connections wit	h all fol	lowing	g poin	ts 4.3.	Χ					Che	ck for	cont	inuity	,		
4.4.2	Controller PE to Protec	tion Cl	ass 1 e	quipn	nent			Brak	e coil	, force	ed co	oling,	lighti	ing,	. 🔲		
	(Protection Class1 = protecti	ve condu	ictor red	quired f	or expo	sed-co	nductive	e-parts)									
4.4.3	Controller PE to car to	conne	ection	box													
	Measure resistance be	tween	car ga	te and	landi	ng do	or frar	ne wit	h car d	doors	open.						
4.4.4	Car top socket PE to do	or ope	rator														
	Car top socket PE to ca	r				С	heck f	or con	tinuity	/							
4.4.5	Car top socket PE to ca	r top c	ontrol	(Prote	ection	Class	1)										
4.4.6	EMC compliant installa	ition of	moto	r and	data c	ables,	, i.e. se	gregat	ion.							Re	quirement in
	Adequate earthing of o									menda	ations	using	specia	al clan	nps.	inve	rter systems!
	Minimum cross sectional are	ea (csa) fo	or main	protect	ive bon	ding co	nducto	rs = 10m	ım²								
5	Voltage Measurement	:s															
	In an arian 14 13			71									1 v4.	200			1/0.0
5.1	Incoming L1 - L2 Incoming L1 - L3		VAC C		ming trol X				 	VAC		Contro Group					VDC
5.3	Incoming L1 - N		VAC [_			: L5 -1	NA.	\vdash	VAC		Car X					VDC
5.4	Incoming L2 - N		VAC [_			(1: L7			VAC		•			_		v
==	Chark the Voltage dea	_	- N	//00	rovim	40	OV-N-	t 4% S	161/1			a pprox	imete	230/-	Nat A	% < 0 °	2//\
5.5	Check the Voltage dro						OV-IVE	L 4/0 S	LOVI			e pprox	imete	2504-	NEL 4	70 2 3,1	
6	Phase Rotation Test of		_											OK-	· 🗹	C	omments
	Г				iuiii St	4PPIY								OK-			
6.1	Clockwise phase rotati	on pres	ent												Ш		
7	Functional Test													OK:	= i ⊘	Co	omments
7.1	Machine, locks and saf	oty dos	sivos b	ave be	on to	ctod f	unctio	nally									
7.2	The safety requiremen					steu i	unctio	many.							뷞		
7.2*	The salety requirement	L3 Have	been	TOTION	reu.										퓜		
7.5	* = available for additions																
						_											
Com	ments*					D	etails	of test	instru	ıment	s used	d (and	serial	numb	ers)		
	*All detected faults or missir	ng compo	onents n	nust be	correct	ed to e	ensure th	hat the o	control	system	compli	es with	the requ	uireme	nts.		



Date Tester signature

EMC Information / Recommendations for Inverter Controlled Systems

Electromagnetic shielding and EMC-compatible wireing





The earthing of the shielding and the quality of the connection to the shielding affect the over all-effect of the electromagnetic shielding!

 Connect the shielding to the Earth Potential as shown in Figure 1 keeping the cables as short as possible.

 Segregate high voltage and high current cables (Motor cable, Brake Resistor cable) from signal cables (Encoder cable, Bus cable) as far as possible >10 cm distance. Cross disturbed cables (Motor cable) in a 90° angle with undisturbed cables (Signal Cables).

 Connect the EMC protection decives shown in the electrical drawings to disturbing sources such as (Contactors, Brakes, Door operators etc.) 5. Do <u>not</u> mount the brake resistor to the housing of the V/V/F inverter or the control cabinet.

6. Connect the shielding with maximal surface to Ground Potential (see Figure 2, 3 and 4)

B. Do not conduct potential equalisation currents via the shielding. Separate potential equalisation cables are mandatory inbetween the different installation.

Ensure that the slope resistance of the shielding is not higher than 0.3 Ohm

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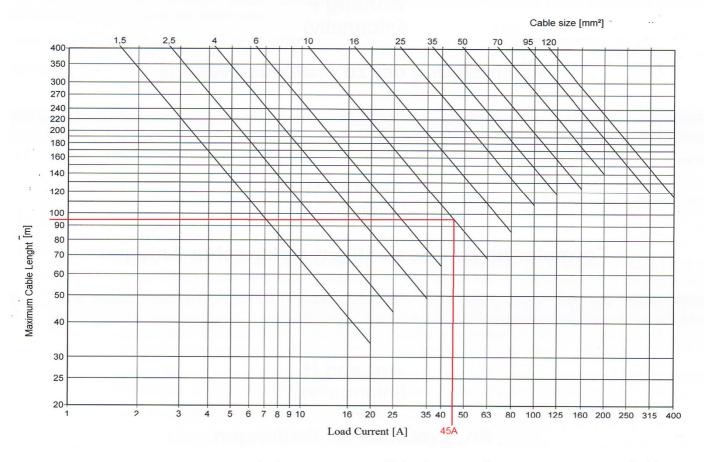


Appendix D - Diagramme for Determining Voltage Drop

Source: DIN VDE0100Part600

Use the cable cross sectional area in conjunction with cable length, conductor temperature and the design current to check whether the applicable voltage drop is acceptable.

The diagramme shows the maximum permissible cable length, based on a 400V 3-phase supply and 55°C conductor temperature, and the resulting 4% voltage drop in relation to the design current.



Note: The diagramme is not suitable for determining the current-carrying capacity of cables.

The indicated values are applicable to 3-phase 400V AC supplies. For single phase 230V AC supplies, divide the cable length by 2.

Example: The design current of a consumer is 45A and the supply length from the substation to the machine room is 70m. A 5x10mm² cable was used for the installation, protected with 50A.

Question: Is the voltage drop acceptable? ==> Yes, according to the diagramme it is suitable up to 95m.

To check the result, calculate the voltage drop:

= √3 x l x l-Nenn x cos/ Kappa x A

= 1,73 x 70m x 45A x 0,9 / 56 x10mm² = 8,82V